

Wireless networked control of a mining ventilation system



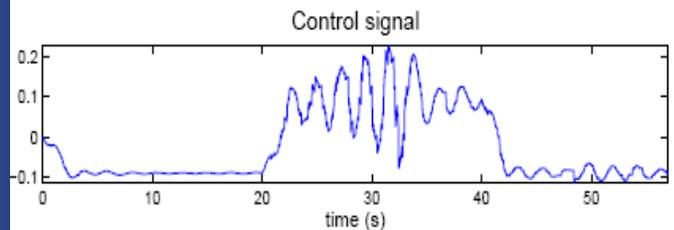
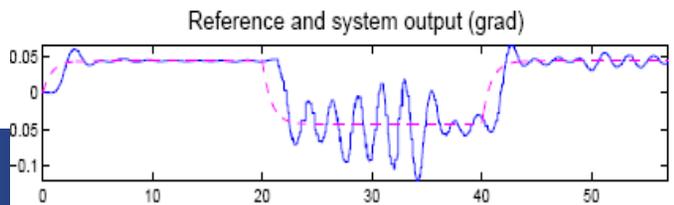
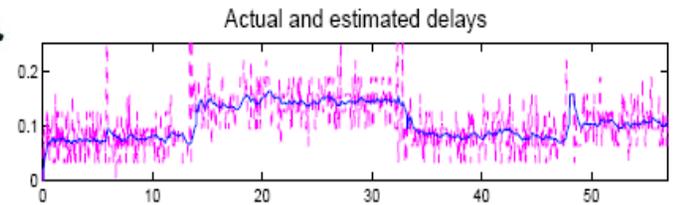
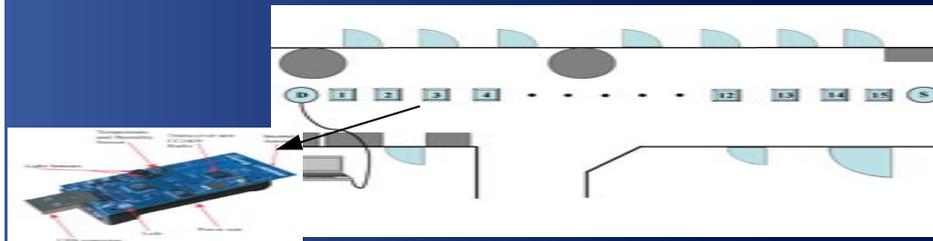
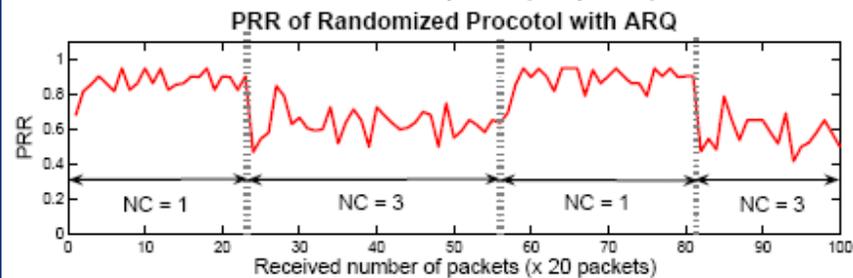
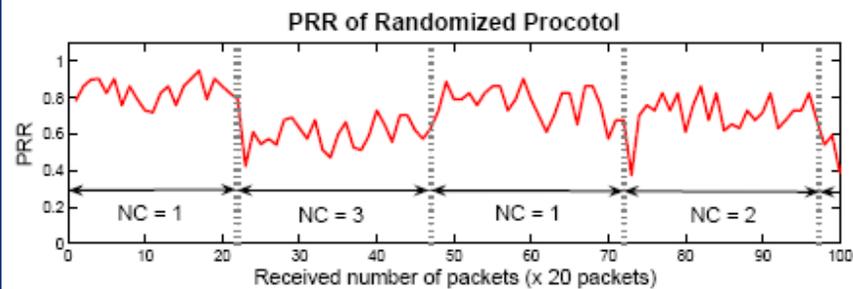
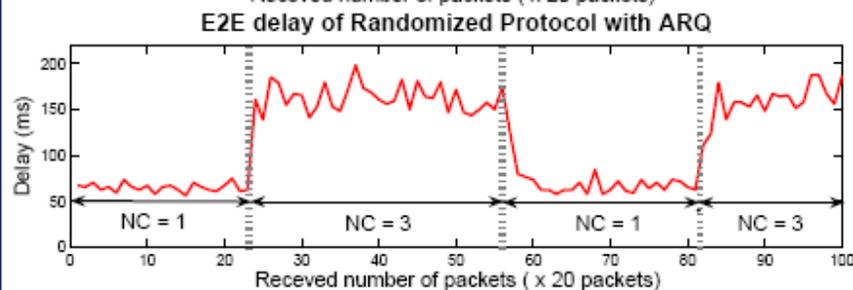
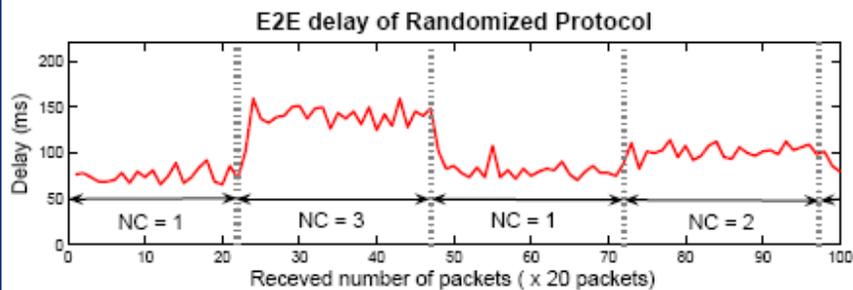
University of L'Aquila



HYCON D4d.5.1: Definition of extracted control problem for industrial test case on wireless automation

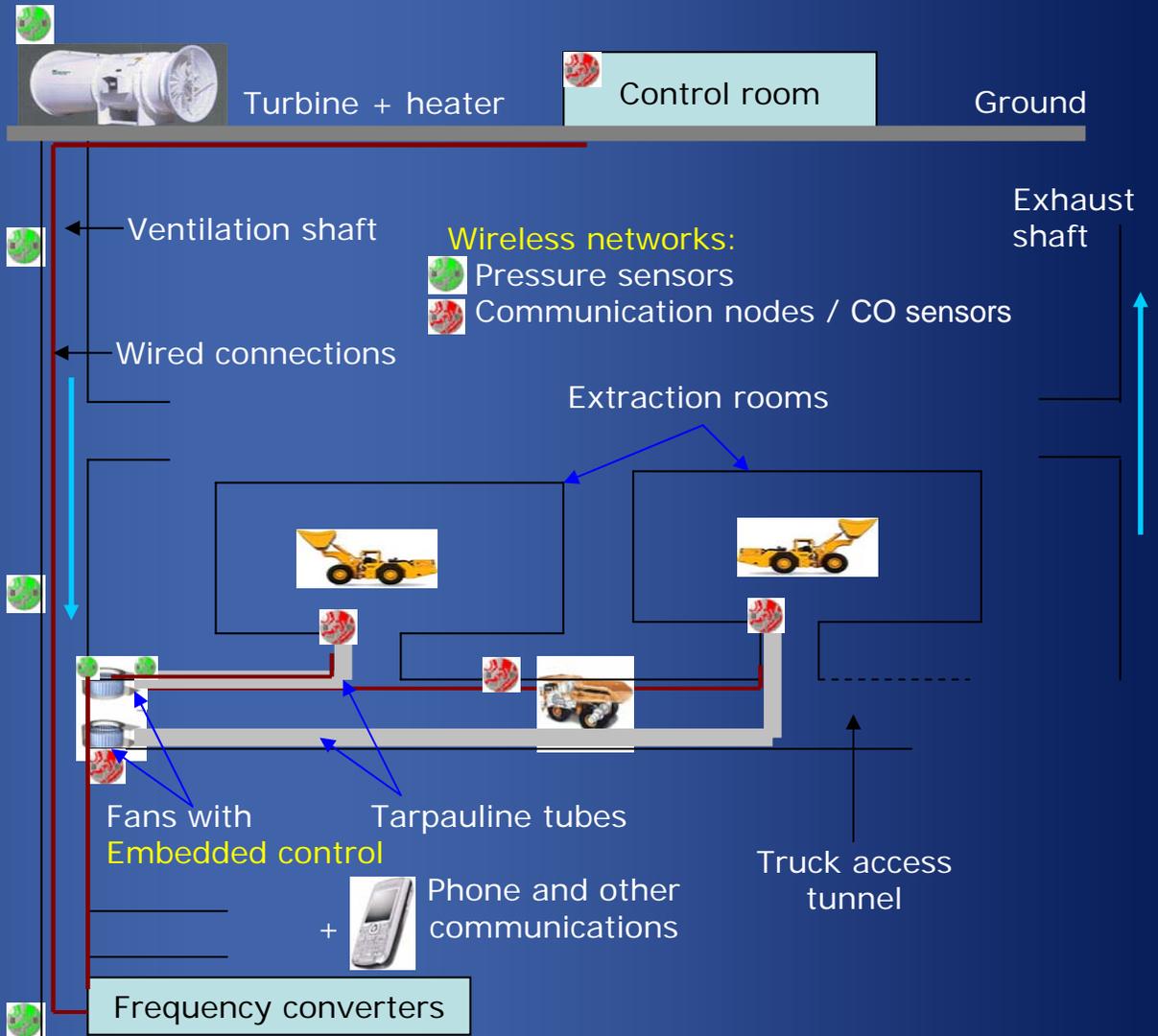
Challenges in control over multi-hop wireless networks

- Innovation:
 - Distributed smart embedded devices
 - Flexibility, deployment in automation
 - Large scale systems with complex dynamics
 - Integrate **computation and communication in distributed control**
- Technical issues:
 - Congestion - resource allocation
 - Information availability
 - Control under generalized constraints (physical, transmission...)



Explicit delay/jitter compensation

⇒ Integrated control approach



⇒ Minimize the amount of fresh air to save energy

- Embedded fan control:
 - Hybrid control (threshold) based on average CO values
- Control room:
 - Use distributed measurements to **reduce model complexity**
 - Model-based control under physical & communication constraints
- Sensors and communication network:
 - Heterogeneous (wired-wireless) architecture
 - Uniform radio technology

$$\tau(t) = n(t)F + \sum_{i=1}^{n(t)} (\alpha_i + \beta_i)$$

Compressible and viscous laminar flow

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} &= 0 \\ \rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} \right) &= -\frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left[(\lambda + 2\mu) \frac{\partial u}{\partial x} \right] + \frac{\partial}{\partial y} \left(\mu \frac{\partial u}{\partial y} \right) \\ \frac{\partial p}{\partial y} &= \frac{\partial}{\partial x} \left(\mu \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial y} \left(\lambda \frac{\partial u}{\partial x} \right) \\ \rho c_v \left(\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} \right) + \left(p + \frac{\rho u}{2} + \rho c_v T \right) \frac{\partial u}{\partial x} &= \rho \dot{q} + \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) \\ &+ \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + (\lambda + 2\mu) \left(\frac{\partial u}{\partial x} \right)^2 + \mu \left(\frac{\partial u}{\partial y} \right)^2 \\ p &= \rho RT \end{aligned}$$



Distributed pressure sensors

$$\dot{p}(t) = Ap(t) + B \int_{-\tau(t)}^0 h(\theta) u(t - \theta) d\theta, \quad p(0) = p_0$$

Time-delay system

Motivation

Information technology components are increasingly used in complex engineering systems. The fundamental problems are essential both technologically and economically.

Need

The pervasive infiltration of computer systems (embedded systems and networks) in engineered products and in medicine and biology, requires transformational thinking and ideas in engineering research, education and entrepreneurship.

Our view point

- To use **model-based system integration methodology** combined with an **overall emphasis on compositional design methodology**. NEW DISCIPLINE!
- The first very important step is to find a correct model of the system and its constraints such that it is in the same time **theoretically plausible** and **practically credible**.

HOW to work?

EECI provides the right framework for this new discipline. Its role:

The establishment of the EECI is expected:

➤ to become a **long-term world-wide** renowned focal point by stimulating new collaborative (multi-national and multi-disciplinary) research on networked and embedded control



- to **break down the barriers** between the traditional disciplines
- to be a motor for the **dissemination** of methods and tools
- to promote the **education** of students and researchers and to transform engineering education
- to encourage the **transfer of methodologies** to industry and to learn new ways to enhance the transfer of innovation to products and the creation of an entrepreneurship culture

➤ to **seek financial support** from both industry (through industrial projects and teaching) and European and national research foundations



From the



Network of Excellence

www.ist-hycon.org

to the creation of



the European Embedded Control Institute

www.eeci-institute.eu



The HYCON NoE and its newly created institute EECI (*under French Association Law 1901*), which offers a legal structure for the Knowledge Community of Networked and Embedded Control, is **very interested to contribute to the actions within ARTEMIS**, providing **methods and tools** to reduce the effort for the design, implementation, and maintenance of high-performance embedded control systems.