

Digital Control Systems

Design, identification and implementation

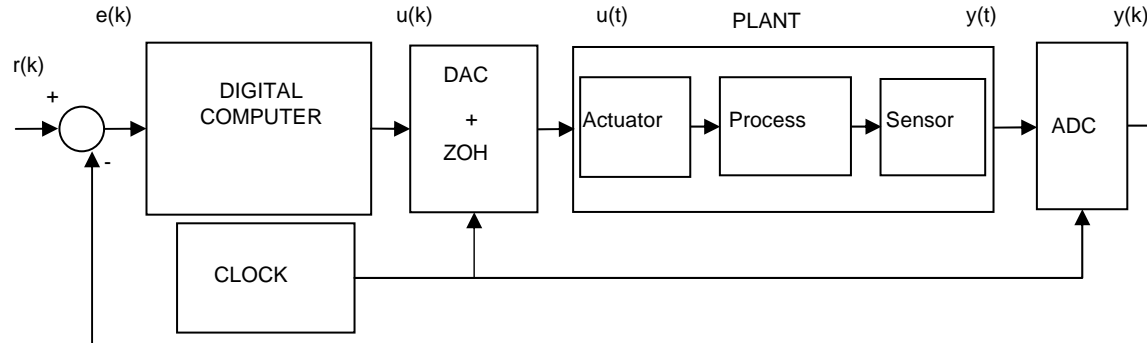
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The object of study

Digital Control System

The *control law* is implemented on a digital computer



ADC: analog to digital converter

DAC: digital to analog converter

ZOH: zero order hold

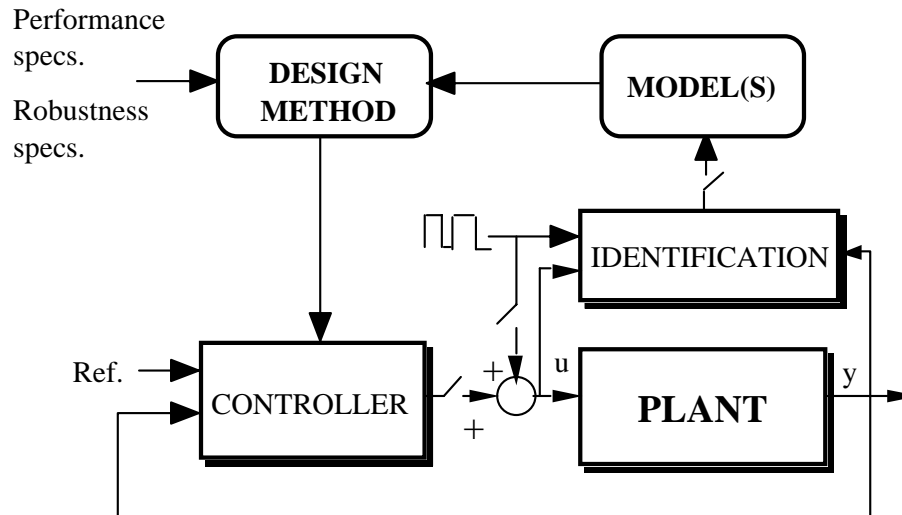
Some preliminary remarks

- Almost all control systems built now use *microprocessors*
- To take advantage of the capabilities of microprocessors, specific *model based* design techniques should be used
- The digital control design techniques have known an important development and have been tested extensively in industry
- The development of control design software has modified the design procedure
- Computer-aided control design software requires the understanding of a number of concepts in order to be used efficiently

Objectives of the book

- To give the necessary knowledge for the understanding and the design of computer controlled systems for varied types of applications
- Presentation oriented towards the need of the designer and user of control systems
- Illustrate by examples and practical realizations the design and implementation methodology

The main stream



To design and tune a good controller one needs :

- To specify the desired control loop performance and robustness
- To know the dynamic model of the plant to be controlled
- To possess a suitable controller design method
- To implement the resulting controller taking into account practical constraints
- To validate the controller performance on site and, if necessary, to re-tune it

How to achieve a « good control»

- A relevant *dynamic model* of the plant is necessary
- *System identification* allows to extract a dynamic model of the plant from input/output measurements
- *System identification* is a key factor for obtaining a high performance control and for shortening the on site tuning
- Based on the identified model, an appropriate *controller* is designed for achieving the desired performance
- The knowledge of data acquisition techniques and implementation of digital algorithms is also necessary
- This design methodology is often called MBC (model based control)

Content

- Chapter 1 : Continuous Control Systems: A Review
- Chapter 2 : Computer Control Systems
- Chapter 3 : Robust Digital Controller Design Methods
- Chapter 4 : Design of Digital Controllers in the Presence of
Random Disturbances
- Chapter 5 : System Identification: The Bases
- Chapter 6 : System Identification Methods
- Chapter 7 : Practical Aspects of System Identification
- Chapitre 8 : Practical Aspects of Digital Control
- Chapter 9 : Identification in Closed Loop
- Chapter 10 : Reduction of Controller Complexity
- Appendices A through H (see the website)

Logical dependence of the various chapters

