

---

## References

- Adaptech (1996a) WinPIM<sup>+</sup>TR – System Identification Software, Adaptech, St. Martin d'Hères, France.
- Adaptech (1997b) WinPIM-BF – Software for closed loop identification, Adaptech, St. Martin d'Hères, France.
- Adaptech (1998) Optreg – Software for automated design of robust digital controllers using convex optimization (for MATLAB<sup>®</sup>), Adaptech, St. Martin d'Hères, France.
- Adaptech (1999a) REDUC – Controller order reduction by closed-loop identification (Toolbox for MATLAB<sup>®</sup>), Adaptech, St. Martin d'Hères, France
- Adaptech (1999b) CLID – Plant model identification in closed loop (Toolbox for MATLAB<sup>®</sup>), Adaptech, St. Martin d'Hères, France.
- Adaptech (2001a) Guidelines for RST controller implementation, Adaptech, St. Martin d'Hères, France.
- Adaptech (2001) Guidelines for PRBS integration, Adaptech, St. Martin d'Hères, France.
- Adaptech (2004) Wintrac – Software for data acquisition and real time RST digital control, Adaptech, St. Martin d'Hères, France.
- Anderson B.D.O., Liu Y. (1989) Controller reduction concepts and approaches , IEEE Trans. on Automatic Control, vol. 34, no. 8, pp. 802-812.
- Anderson B.D.O. (1993) Controller reduction: moving from theory to practice , IEEE Control Magazine, vol. 13, pp. 16-25.
- Anderson B.D.O. (1998) From Youla Kučera to identification, adaptive and nonlinear control, Automatica vol. 34, 1485-1506.
- Anderson B.D.O., Moore J.B. (1971) Linear Optimal Control, Prentice Hall, Englewood Cliffs, N.J.
- Aström K.J. (1970) Introduction to Stochastic Control Theory, Academic Press, N.Y.
- Aström K.J., Hägglund I. (1995) PID Controllers Theory, Design and Tuning, 2nd edition ISA, Research Triangle Park, N.C., U.S.A.
- Aström K.J., Wittenmark B. (1995) Adaptive Control, 2nd edition, Addison Wesley, Reading, Mass.
- Aström K.J., Wittenmark B. (1997) Computer Controlled Systems - Theory and Design, 3rd edition, Prentice-Hall, Englewood Cliffs, N.J.
- Bendat J.S., Piersol A.G. (1971) Random Data Analysis and Measurement Procedures, John Wiley.
- Béthoux G. (1976) Approche unitaire des méthodes d'identification et de commande adaptative des procédés dynamiques, Ph.D., Institut National Polytechnique de Grenoble, juillet.

- Bierman, G. (1977) Factorization methods for discrete sequential estimation, Academic Press, New York.
- Bourlès H., Irving E. (1991) La méthode LQG/LTR une interprétation polynomiale, temps continu/temps discret , RAIRO-APII, Vol. 25, pp. 545-568.
- Box G.E.P., Jenkins G.M. (1970) Time Series Analysis , Forecasting and Control, Holden Day, S. Francisco.
- Boyd St.P, Barratt C.H. (1991) Linear controller design. Limits of performance, Prentice Hall, Englewood Cliffs.
- Camacho, E.F., Bordons, C. (2004) Model Predictive Control, 2nd edition, Springer, London, UK.
- Candy J.V. (1986) Signal Processing - The Model Based Approach, MacGraw-Hill, N.Y.
- Clarke D.W., Gawthrop P.J. (1975) A Self-Tuning Controller , Proc. IEE, vol.122, pp. 929-34.
- Clarke D.W., Gawthrop P.J. (1979) Self-tuning Control , Proc. IEEE, vol. 126, pp .633-40.
- Clarke D., Mothadi C. (1987) Generalized predictive control, Automatica, vol 23, pp. 137-160.
- Clarke D., Mothadi C. (1989) Properties of generalized predictive control, Automatica, vol 25, pp. 859-876.
- Doyle J.C., Francis B.A., Tanenbaum A.R.,(1992) Feedback Control Theory, Mac Millan, N.Y.
- Dugard L., Landau I.D. (1980) Recursive Output Error Identification Algorithms Theory and Evaluation , Automatica, vol. 16, pp.443-462.
- Duong H.N., Landau I.D. (1996) An I.V. based criterion for model order selection , Automatica, vol. 32, no. 6, pp. 909-914.
- Eykhoff P. (1974) System Identification Parameter and State Estimation, John Wiley, London.
- Fenot C., Rolland F., Vigneron G., Landau I.D. (1993) Open loop adaptive feedback control of depozited zinc in hot dip galvanizing , Control Engineering Practice, vol. 1, no. 5, pp 347-352.
- Fenot C., Vigneron G., Rolland F., Landau I.D. (1993) Régulation d'épaisseur de dépôt de zinc à Sollac, Florange , Revue Générale d'Electricité, no. 11, pp. 25-30, Déc.
- Forsell U., Ljung L. (1999) Closed loop identification revisited, Automatica, vol. 35, n. 7, pp. 1215-1241.
- Franklin G., Powell J.D. (1986) Feedback Control of Dynamic Systems, Addison Wesley, Reading, Mass.
- Franklin G.F., Powell J.D., Workman M.L. (1998) Digital Control of Dynamic Systems , 3<sup>rd</sup> edition, Addison Wesley, Reading, Mass.
- Gevers M. (1993) Towards a joint design of identification and control , in Essays in Control (H.L. Trentelman, J.C. Willems, Eds), Birkhäuser, Boston, USA, pp. 111-152.
- Goodwin G.C., Payne R.L. (1977) Dynamic System Identification Experiment Design and Data Analysis, Academic Press, N.Y.
- Goodwin G.C., Sin K.S. (1984) Adaptive Filtering Prediction and Control, Prentice-Hall, Englewood Cliffs, N.J.
- Hogg R., Graig A. (1970) Introduction to Mathematical Statistics, MacMillan, N.Y.
- Isermann R. (1980) Practical aspects of process identification , Automatica, vol.16, pp. 575-587.
- Isermann R. (Ed) (1981) Special Issue on System Identification , Automatica, vol 17, n° 1.
- Kailath T. (1980) Linear systems, Prentice Hall, Englewood Cliffs, N.J.
- Karimi A., Landau I.D. (1998) Comparison of the closed loop identification methods in terms of the bias distribution , Systems and Control Letters, vol. 34, pp. 159-167.
- Kuo B. (1980) Digital Control Systems, Holt Saunders, Tokyo.
- Kuo B.C. (1991) Automatic Control Systems (6th edition), Prentice Hall, N.J.

- Kwakernaak H. (1993) Robust control and  $H_{\inf}$  optimization – a tutorial Automatica, vol.29, pp.255-273.
- Landau I.D. (1976) Unbiased recursive identification using model reference adaptive techniques I.E.E.E., Trans. on Automatic Control, vol AC-20, n°2, pp. 194-202.
- Landau I.D. (1979) Adaptive control – the model reference approach, Dekker, N.Y.
- Landau I.D. (1981) Model Reference Adaptive Controllers and Stochastic Self-tuning Regulators, A Unified Approach , Trans. A.S.M.E. J. of Dyn. Syst. Meas. and Control, vol. 103, n°4, pp. 404, 416.
- Landau I.D. (1982) Near Supermartingales for Convergence Analysis or Recursive Identification and Adaptative Control Schemes , Int J. of Control, vol.35, pp. 197-226.
- Landau I.D. (1984) A Feedback System Approach to Adaptive filtering , IEEE Trans. on Information Theory, vol. 30, n°2, pp. 251-262.
- Landau I.D. (1986) La Commande Adaptative Un Tour Guidé, in Commande adaptative - Aspects pratiques et théoriques (Landau, Dugard- Editeurs), Masson, Paris.
- Landau I.D. (1990) System Identification and Control Design, Prentice Hall, Englewood Cliffs, N.J.
- Landau I.D. (1993) Evolution of Adaptive Control , A.S.M.E. Transactions, Journal D.S.M.C., vol. 115, no. 2, pp. 381-391, june.
- Landau I.D. (1995) Robust digital control of systems with time delay (the Smith predictor revisited) , Int. J. of Control, vol. 62, pp. 325-347.
- Landau I.D. (2001a) Identification in closed loop a powerful design tool (better models, simple controllers) , Control Engineering Practice, vol. 9, no. 1, pp. 51-65.
- Landau I.D. (2001b) Les bases de l'identification des systèmes, in Identification des Systèmes (I.D. Landau, A. Bensançon-Voda, ed), pp. 19-130, Hermès, Paris.
- Landau I.D., Constantinescu A., Rey D. (2005) Adaptive Narrow Band Disturbance Rejection Applied to an Active Suspension – An Internal Model Principle Approach, Automatica, Vol.61, n°4.
- Landau I.D., Karimi A. (1997a) An output error recursive algorithm for unbiased identification in closed loop , Automatica, vol. 33, no. 8, pp. 933-938.
- Landau I.D., Karimi A. (1997b) Recursive algorithms for identification in closed-loop – a unified approach and evaluation , Automatica, vol. 33, no. 8, pp. 1499-1523.
- Landau I.D., Karimi A. (1998) Robust digital control using pole placement with sensitivity function shaping method , Int. J. of Robust and Nonlinear Control, vol. 8, pp. 191-210.
- Landau I.D., Karimi A. (2001) Identification des modèles de procédé en boucle fermée , in Identification de systèmes (I.D. Landau, A. Besançon-Voda, Eds), pp. 213-244, Hermès, Paris.
- Landau I.D., Karimi A. (2002) A unified approach to closed-loop plant identification and direct controller reduction, European J. of Control, vol. 8, no.6.
- Landau I.D., Karimi A., Constantinescu A. (2001) Direct controller reduction by identification in closed loop , Automatica, vol. 37, no. 11, pp. 1689-1702.
- Landau I.D., Langer J., Rey D., Barnier J. (1996) Robust control of a 360° flexible arm using the combined pole placement / sensitivity function shaping method , IEEE Trans. on Control Systems Tech., vol. 4, no. 4, pp. 369-383.
- Landau I.D., Lozano R. (1981) Unification of Discrete-Time Explicit Model Reference Adaptive Control Designs , Automatica, vol. 12, pp. 593-611.
- Landau I.D., Lozano R., M'Saad M. (1997) Adaptive Control, Springer, London, UK.
- Landau I.D., M'Sirdi N., M'Saad M. (1986) Techniques de modélisation récursives pour l'analyse spectrale paramétrique adaptative , Traitement du Signal, vol.3, pp. 183-204.
- Landau I.D., Rolland F. (1993) Identification and digital control of electrical drives , Control Engineering Practice, vol. 1, no. 3.

476 References

- Langer J., Constantinescu A. (1999) Pole placement design using convex optimization criteria for the flexible transmission benchmark , European Journal of Control, vol. 5, no. 2-4, pp. 193-207.
- Langer J., Landau I.D. (1996) Improvement of robust digital control by identification in closed loop. Application to a 360° flexible arm , Control Engineering Practice, vol. 8, no. 4, pp. 1079-1088.
- Langer J., Landau I.D. (1999) Combined pole placement / sensitivity function shaping using convex optimization criteria , Automatica, vol. 35, pp. 1111-1120.
- Ljung L.,(1999) System Identification - Theory for the User, 2nd edition, Prentice Hall, Englewood Cliffs.
- Ljung L., Söderström T. (1983) Theory and Practice of Recursive Identification, MIT Press, Cambridge, Mass.
- Lozano R., Landau I.D. (1982) Quasi-direct adaptive control for nonminimum phase systems , Transactions A.S.M.E., Journal of D.S.M.C., vol. 104, n°4, pp. 311-316, décembre.
- Macejowski J.M.(2001) Predictive control with constraints, Prentice Hall, N.J.
- Mathworks (1998) Identification toolbox for Matlab, The Mathworks Inc., Mass. U.S.A.
- Morari M., Zafriou E. (1989) Robust Process Control, Prentice Hall International, Englewood Cliffs, N.J.
- M'Saad M., Landau I.D. (1991) Adaptive Control An overview , Actes du Symposium International IFAC ADCHEM 91, pp.3-11, Toulouse.
- Narendra K.S., Taylor J.H. (1973) Frequency Domain Criteria for Absolute Stability, Academic Press, New York.
- Ogata K. (1990) Modern Control Engineering (2nd edition), Prentice Hall, N.J.
- Ogata K. (1987) Discrete-Time Control Systems, Prentice Hall, N.J.
- Phillips, C.L., Nagle, H.T. (1995) Digital Control Systems Analysis and Design, 3rd edition, Prentice Hall, N.J.
- Press W.H., Vetterling W.T., Teukolsky S., Flanery B. (1992) Numerical recipes in C (The art of scientific computing), 2nd edition, Cambridge University Press, Cambridge, Mass.
- Prochazka H., Landau I.D. (2003) Pole placement with sensitivity function shaping using 2nd order digital notch filters, Automatica, Vol. 39, 6, pp. 1103-1107.
- Rantzer A., Megretski A. (1994) A convex parametrization of robustly stabilizing controllers, IEEE Trans. Aut. Control. Vol. 39, pp. 1802-1808.
- Rolland F., Landau I.D. (1991) Pour mieux réguler le PC va vous aider , Mesures, pp. 71-73, décembre.
- Shinskey F.G. (1979) Process Control Systems, McGraw-Hill, N.Y.
- Söderström T., Stoica P. (1983) Instrumental variable methods for system identification , Lectures Notes in Control and Information Sciences, Springer Verlag, Berlin.
- Söderström T., Stoica P. (1989) System Identification, Prentice Hall International, Hertfordshire.
- Solo V. (1979) The Convergence of A.M.L. , IEEE Trans. Automatic Control, vol. AC-24, pp. 958-963.
- Sung H.K., Hara S. (1988) Properties of sensitivity and complementary sensitivity functions in single-input, single-output digital systems , Int. J. of Cont., vol. 48, n°6, pp. 2429-2439.
- Takahashi Y., Rabins M., Auslander D. (1970) Control, Addison Wesley, Reading, Mass.
- Tsyplkin Y.Z. (1997) Stochastic discrete systems with internal models, Journal of Automation and information Sciences, Vol. 29 pp. 156-161.
- Van den Bossche E. (1987) Etude et commande adaptative d'un bras manipulateur flexible , Ph.D., I.N.P.G.

- Van den Hof P., Shrama R. (1993) An indirect method for transfer function estimation from closed loop data , Automatica, vol. 29, no. 6, pp. 1523-1528.
- Vieillard J.P. (1991) Machine automatique pour la fabrication de cables torsadés téléphoniques , La Lettre d'Adaptech, no. 2, pp. 1-2, Adaptech, St. Martin d'Hères, France.
- Vinnicombe G. (1993) Frequency domain uncertainty and the graph topology , IEEE Trans. on Automatic Control, vol. 38, no. 9, pp. 1371-1383.
- Voda A., Landau I.D. (1995a) A method for the auto-calibration of P.I.D. controllers , Automatica, no. 2.
- Voda A., Landau I.D. (1995b) The auto-calibration of P.I. controllers based on two frequency measurements , Int. J. of Adaptive Control and Signal Processing, vol. 9, no. 5, pp. 395-422.
- Wirk G.S. (1991) Digital Computer Systems, 3rd edition, MacMillan, London.
- Young P.C. (1969) An Instrumental Variable Method for Real Time Identification of a Noisy Process , Automatica, vol.6, pp. 271-288.
- Young P.C., Jakeman A.J. (1979) Refined Instrumental Variable Methods of Recursive Time Series Analysis , Part I, Single-input, Single-output Systems, Int. J. of Control, vol. 29, pp.1-30.
- Zames G. (1966) On the input-output stability of time-varying non linear feedback systems , IEEE-TAC, vol. AC-11, April, pp. 228-238, july pp. 445-476.
- Zhu K. (1998) Essentials of robust control, Prentice Hall, N.J., U.S.A.
- Ziegler J.G., Nichols N.B. (1942) Optimum Settings for Automatic Controllers , Trans. ASME, vol. 64, pp. 759-768.