

Distributed averaging on digital noisy networks

Paolo Frasca

Dipartimento di Matematica

Politecnico di Torino

Torino, Italy

<http://calvino.polito.it/~frasca>

joint work with R. Carli (UCSB), G. Como (MIT), F. Garin (INRIA)

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 - 3 Performance measures
 - 4 A poly-logarithmic algorithm
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The averaging problem

The averaging problem

Digital com- munication

Performance measures

A poly- logarithmic algorithm

Given

- a strongly connected **graph** $\mathcal{G} = (V, E)$, $|V| = N$
 - nodes are **agents**;
 - edges are available **communication channels**.
- $\forall v \in V, \theta_v \in \mathbb{R}$.

We want to compute the **average**

$$y = \frac{1}{N} \sum_{v \in V} \theta_v.$$

in spite of the communication limitations.

Linear averaging algorithm

Proposition

Let $\mathbf{x}(k+1) = P\mathbf{x}(k)$, and $\mathbf{x}(0) = \boldsymbol{\theta}$, with P adapted to \mathcal{G} . If P is doubly stochastic and has positive diagonal

\implies the algorithm converges to the average:

$$\lim_{k \rightarrow \infty} x_v(k) = y \quad \forall v \in V.$$

Moreover, let

$$n(\delta) := \inf \left\{ n \in \mathbb{N} : N^{-1} \|\mathbf{x}(n) - y\mathbf{1}\|^2 \leq \delta, \forall m \geq n \right\}.$$

Then,

$$n(\delta) \leq C \frac{\log \delta^{-1}}{\log \rho^{-1}},$$

where ρ is the second largest eigenvalue of P .

But this algorithm requires communication of **real numbers!**

Can a network of **digital noisy channels** be used to compute averages?

To answer this question we need

- a model for digital communication and computation;
- useful convergence and performance notions;
- (possibly) algorithms solving the problem.

Digital broadcast communication

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At each time instant $t \in \mathbb{N}$,

- every agent $v \in V$ broadcasts a **binary signal** $a_v(t) \in \{0, 1\}$ to its out-neighbourhood \mathcal{N}_v^+ ;
- every agent $w \in \mathcal{N}_v^+$ receives a **possibly erased** version $b_{v \rightarrow w}(t) \in \{0, 1, ?\}$ of $a_v(t)$;
- each agent $v \in V$ makes an **estimate** $\hat{y}_v(t)$ of y .

We assume that

- the communication network is memoryless;
- for every $v \in V$, $w \in \mathcal{N}_v^+$, and $t \in \mathbb{N}$,

$$b_{v \rightarrow w}(t) = \begin{cases} ? & \text{w.p. } \varepsilon \\ a_v(t) & \text{w.p. } 1 - \varepsilon. \end{cases}$$

Performance measures I

Given a required precision $\delta \in]0, 1]$, we define two **complexity figures**.

- **Communication complexity**

$$\tau(\delta) := \inf \{ t \in \mathbb{N} : N^{-1} \mathbb{E} [\|\hat{\mathbf{y}}(s) - y\mathbf{1}\|^2] \leq \delta, \forall s \geq t \} ,$$

the minimum number of binary transmissions each agent has to perform in order to guarantee that the average mean squared estimation error does not exceed δ .

Performance measures II

- *Computational complexity*:
denote by $\kappa_v(t)$ the minimum number of operations required by agent v for to compute $\alpha_v(t)$ and $\hat{y}_v(t)$; define

$$\kappa(\delta) := \max \left\{ \sum_{1 \leq t \leq \tau(\delta)} \kappa_v(t) : v \in V \right\},$$

the maximum, over all agents $v \in V$, of the total number of operations required to be performed, in order to achieve an average mean squared estimation error not exceeding δ .

Algorithm I

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We want to adapt to the digital setting the linear update

$$x_v(j+1) = \sum_{w \in \mathcal{N}_v^-} P_{vw} x_w(j) + P_{vv} x_v(j).$$

But x_w can not be transmitted as such on a noisy channel!
Instead, $v \in \mathcal{N}_w^+$ can only obtain, after some binary transmissions, an estimate $\hat{x}_w^{(v)}$.

A solution consists in alternating

- transmission phases of increasing length $\ell_j = S_L j$
- averaging steps

$$x_v(j+1) = \sum_{w \in \mathcal{N}_v^-} P_{vw} \hat{x}_w^{(v)}(j) + P_{vv} x_v(j).$$

Algorithm II

- During transmission, agents use *linear tree codes*, which [CFZ08] allow $u \in \mathbb{R}$ to be transmitted with precision

$$\mathbb{E} [(u - \hat{u}_\ell)^2] \leq \beta_L^{2\ell},$$

requiring a number of operations $k_\ell^L \leq B\ell^3$, for all $\ell \geq 0$, where $\beta_L \in (0, 1)$, and $B > 0$ are constants depending on the erasure probability ε only.

- why increasing length of transmission phases?*
Increasing length, precision is increased.
If precision is not increased, the committed errors accumulate, and $\mathbf{x}(t)$ does not converge [XBK07].

Result

Theorem

For any S_L , there exists a real-valued random variable \hat{y} s. t.

- $\mathbb{E} [(y - \hat{y})^2] \leq \frac{\alpha^2}{(1 - \alpha)^2}$, where $\alpha = \beta_L^{S_L}$, and
- with probability one,

$$\lim_{t \rightarrow \infty} \hat{y}_v(t) = \hat{y}, \quad \forall v \in V.$$

Moreover, for all $\delta \in]0, 1]$, one can choose S_L so that

$$\tau_L(\delta) \leq C_1 + C_2 \frac{\log^3 \delta^{-1}}{\log^2 \rho^{-1}}, \quad \kappa_L(\delta) \leq C_3 + C_4 \frac{\log^7 \delta^{-1}}{\log^4 \rho^{-1}},$$

where $\{C_i : i = 1, \dots, 4\}$ are positive constants depending on ε only.

Algorithm variation

Using

- sub-exponential *repetition codes*, which have linear complexity,
- $\ell_j = S_R j^2$,

one obtains a performance

$$\tau_R(\delta) \leq C_5 + C_6 \frac{\log^5 \delta^{-1}}{\log^3 \rho^{-1}}, \quad \kappa_R(\delta) \leq C_7 + C_8 \frac{\log^5 \delta^{-1}}{\log^3 \rho^{-1}},$$

for all $\delta \in]0, 1]$.

Feedback channels

If the channels allow **communication feedback**, the state update step can be replaced by

$$x_v(j+1) = x_v(j) - \sum_{w \in \mathcal{N}_v^+} P_{vw} \hat{x}_v^{(w)}(j) + \sum_{w \in \mathcal{N}_v^-} P_{vw} \hat{x}_w^{(v)}(j).$$

Theorem

For any S_L , then with probability one,

$$\lim_{t \rightarrow \infty} \hat{y}_v(t) = y, \quad \forall v \in V.$$

Moreover, for all $\delta \in]0, 1]$, one can choose S_L so that

$$\tau'_L(\delta) \leq C'_1 + C'_2 \frac{\log^2 \delta^{-1}}{\log^2 \rho^{-1}}, \quad \kappa'_L(\delta) \leq C'_3 + C'_4 \frac{\log^4 \delta^{-1}}{\log^4 \rho^{-1}},$$

where $\{C'_i : i = 1, \dots, 4\}$ are positive constants depending on ε only.

About the presented algorithms:

- Results can be extended from erasure channels to symmetric memoryless channels.
- Why $\log^3(\delta)$ communication complexity?
(# update steps \times initial precision \times increasing precision)
- Performance depends on topology, via ρ .
- No global knowledge (e.g., topology) is required to the agents.
- Communication feedback can be effectively exploited.

Open problem: Is there hope for an algorithm with $\log(\delta)$ communication complexity?

Further reading



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